

1 **Bridge Deck Scanning for Condition Assessment**
2 **of Bare Concrete and Asphalt Overlaid Decks**

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44 **ABSTRACT**

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46 This paper presents technologies used for condition assessment of bare concrete decks and
47 asphalt overlaid decks. The study was funded by the NCHRP-IDEA program. The objective of
48 the research and development was to develop a faster, more accurate technology to determine
49 internal conditions of bridge decks. A Bridge Deck Scanner (BDS) prototype with a pair of
50 transducer wheels was originally developed. Later the BDS system was expanded as part of a
51 SHRP 2 R06 (D) research project for asphalt pavement delamination (NCAT study at Auburn
52 University) so that up to three pairs of transducer wheels could be added to the system for more
53 rapid testing. The BDS system can be set to perform either Impact Echo Scanning on all wheels
54 for condition assessment of bare concrete decks or simultaneously perform Impact Echo
55 Scanning and Spectral Analysis of Surface Waves Scanning for condition assessment of concrete
56 decks underneath overlays such as asphalt. In this paper, two case studies are presented (one
57 from a bare concrete deck and one from an asphalt overlaid deck) in which comparison/ground-
58 truthing techniques (sounding, coring, hydro-blasting, etc.) were employed along with BDS
59 results.

60 INTRODUCTION

61

62 Corrosion of reinforcement leading to concrete deck delamination is a major maintenance
63 repair/replacement cost for state DOT's across the country. Accurate mapping of top and bottom
64 delamination is needed to guide repair/replacement decisions. The inspection of concrete bridge
65 decks typically includes a delamination survey (with chain dragging for acoustic sounding that
66 detects top rebar delamination only). Employing innovative scanning NDE systems can improve
67 delamination mapping accuracy, reduce inspection time, and provide additional information
68 regarding possible bottom delaminations as well as the internal concrete conditions such as
69 freeze-thaw and alkali-silica reaction cracking damage. In addition, sophisticated NDE systems
70 can be employed in instances in which traditional chain dragging techniques have not been
71 effective, such as areas with deeper delamination or on asphalt overlaid concrete bridge decks.

72

73 A research project titled "Vehicle-Mounted Bridge Deck Scanner" funded by the NCHRP-IDEA
74 program is summarized herein. This research project focused on the development of rapid
75 inspection techniques by adapting well known NDE test methods into rolling/scanning
76 equipment. The equipment then allowed for rapid testing to provide: (1) top and bottom
77 delamination mapping; (2) internal conditions / deterioration mapping; and (3) thickness
78 profiling. Since development of the system, multiple bridge decks of varying type and condition
79 have been evaluated from bare concrete decks to asphalt overlaid decks. Two case studies (one
80 on a bare concrete deck and one on an asphalt overlaid deck) with actual destructive correlations
81 are presented herein.

82

83 BRIDGE DECK SCANNER

84

85 The Bridge Deck Scanner (BDS) was recently developed by the research team at Olson
86 Engineering as part of research funded by the National Cooperative Highways Research Program
87 – Innovations Deserving Exploratory Analysis program (1). The current BDS system consists of
88 up to three sets of two identical transducer wheels. Figure 1 shows a transducer wheel
89 assembly. The transducer wheel was designed to include six impact echo piezoceramic
90 displacement transducers at 6 inch (152.4 mm) spacings, resulting in a wheel circumference of 3
91 feet (0.91 meter) or a diameter of approximately 11.5 inches (279.4 mm). The 6 inch (152.4
92 mm) transducer spacing was selected to provide relatively close measurement intervals
93 consistent with a high data resolution bridge deck survey. Six displacement transducer elements
94 were incorporated into the wheel. The six transducers were spring mounted with rubber isolators
95 and captured with a thin urethane tire approximately 2.5 inch (63.5 mm) wide that is replaceable.
96 The thin urethane tire was added as a dust cover to prevent dirt from entering the sensor housing
97 and more importantly to increase sensor contact area and coupling. The transducer wheel design
98 of the BDS uses a solenoid impactor to impart energy into the concrete and create high amplitude
99 signals which are easily measured. The urethane tire, larger impacting solenoids, and overall
100 sensor weight (approximately 25 lbs or 11.3 kilogram), which affects contact pressure, are the
101 primary changes that improved the rough surface performance of the BDS system over previous
102 prototypes. Six solenoids per wheel were used in the design. The solenoids were mounted to the
103 side of the rolling transducer wheel in line with the sensor element, thus ensuring the solenoid
104 height (distance between bridge surface and solenoid) remained constant to improve test
105 consistency.

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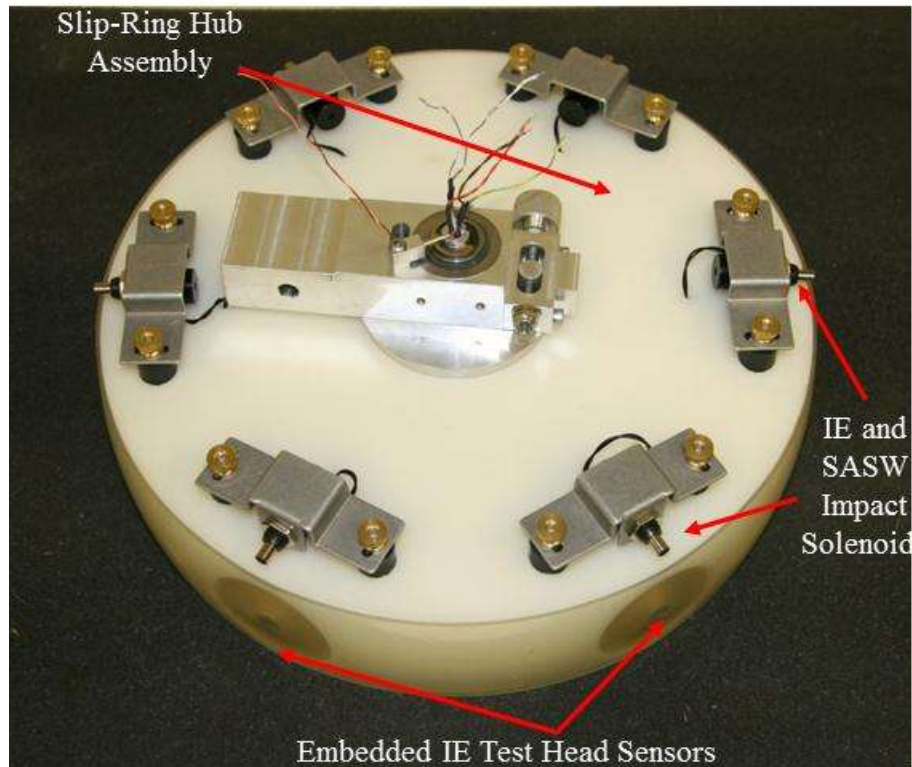


Figure 1 – Transducer Wheel Assembly

The two transducer wheels are identical. The BDS system can be equipped with up to three pairs of transducer wheels and can be easily attached to either a vehicle hitch (if all three pairs of transducer wheels are used) as shown in Figure 2 or a scanning cart (if only a pair of transducer wheels are used) as shown in Figure 3. Each set of transducer wheels of the BDS system can perform:

- 1) Impact Echo tests on both wheels simultaneously in two scan lines (one scan per each wheel) by offsetting the transducer elements (by approximately 3 inches or 76.2 mm) and having the impactors from both wheels turned on. This is a good setup for condition assessment of bare concrete decks if top delaminations and general integrity are the primary concern. Note that the spacing between the two adjacent transducer wheels can be set between 6 inches (0.15 meter) and 2 feet (0.61 meter) depending on the scan resolution desired for the testing.
- 2) Impact Echo and Spectral Analysis of Surface Waves (SASW) scanning simultaneously by aligning the transducer elements of both transducer wheels. The first transducer wheel (with the impactors on) can be used to perform the Impact Echo test. The second wheel (with the impactors off) can be used as the second transducer to acquire data for the SASW test analysis. Note that both Impact Echo and Spectral Analysis of Surface Waves tests can be performed simultaneously in a single scan. This setup provides additional information for complex situations such as assessment of a concrete deck under an asphalt overlay, which, in past experience, has been problematic for IE testing alone.

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Figure 2 – Bridge Deck Scanner Towed behind a Vehicle – 3 pairs of wheels at 2 feet (0.61 meter) apart



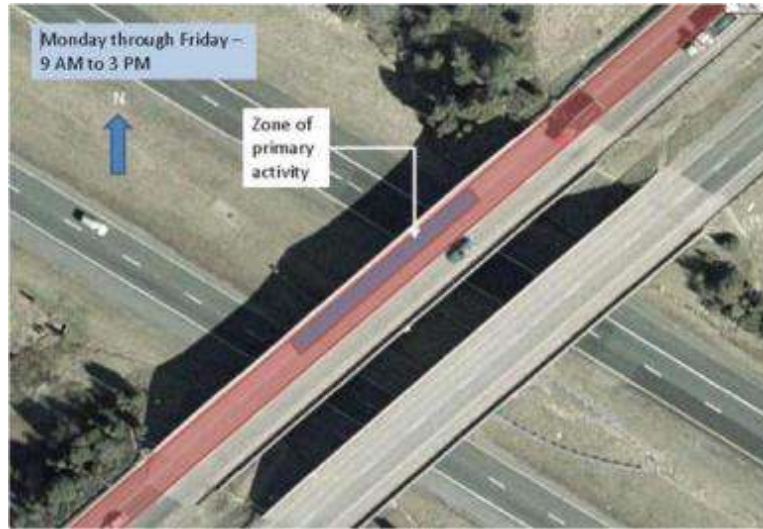
Figure 3 – BDS System Attached to a Scanning Cart on Asphalt Overlaid Deck – Single Pair of Wheels at 6 inches apart for Combined Impact Echo/Surface Waves Scanning

FIRST CASE STUDY: BRIDGE DECK SCANNER USING IMPACT ECHO SCANNING ON A BARE CONCRETE DECK

Project Background

Olson Engineering was invited by Dr. Nenad Gucunski of Rutgers University to participate in the non-destructive evaluation (NDE) validation testing of bridge decks as a part of Rutgers’ Strategic Highway Research Program SHRP 2 R06(A) Bridge Deck Validation research project (2). The selected test bridge is located on James Madison Highway – US 15 over Interstate 66 at Haymarket, Virginia. The area of testing measured 84 feet in length and 12 feet in width. The

198 nominal thickness of the bridge deck is 8.5 inches (215.9 mm). An overview of the bridge and
 199 the investigated area is presented in Figure 4 below.
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 202
 203 **Figure 4 – Overview of Bridge Deck Validation Test Area for James Madison Highway -**
 204 **US 15 over Route 66 near Haymarket, Virginia**

205
 206 **Non-Destructive Evaluation Test Methods for Concrete Bridge Deck Delamination**
 207 **Detection**

208
 209 The field validation was performed by personnel of Olson Engineering, Inc., in November 2010
 210 with assistance by personnel of IDS from Pisa, Italy in the performance of ground penetrating
 211 radar using the Aladdin system which is manufactured by the GeoRadar division of IDS. Non-
 212 destructive evaluation test methods performed by the Olson Engineering team included:

- 213 1) Impact Echo Scanning (IES) using a recently developed Bridge Deck Scanner (BDS)
 214 with a pair of transducer wheels on a 1 foot (304.8 mm) interval across the width of
 215 the lane and 0.5 feet (152.4 mm) interval along the length of the lane
 216 2) Ground Penetrating Radar using a GSSI SIR3000 with a 1.6 GHz ground coupled
 217 antenna and an IDS Aladdin GPR system with a 2.0 GHz ground coupled bi-polar
 218 antenna (test results are not presented in the paper).

219 The background and theory of Impact Echo (IE) test can be found in many publications (1, 2 and
 220 3). Note that the Impact Echo Scanning technique has been previously used with excellent
 221 correlation between the BDS-IE test results and acoustic sounding on other bridges (2).
 222

223 **Test Results from the BDS-Impact Echo Scanning**

224
 225 The graphical IES test results from the Bridge Deck Scanner are presented in Figure 5. The
 226 thickness results from the IES tests were normalized by the nominal thickness of the tested line.
 227 A global normalization could not be applied because the thicknesses of the concrete deck along
 228 the C and D Test Lines (5 feet (1.52 meters) and 6 feet (1.83 meters) east of Line A) were thicker
 229 than the design thickness of 8.5 inches (215.9 mm). It is assumed that this area was thickened to

230 provide additional bearing support, as this was at a location of one of the supporting steel girders.
231 The plot is a normalized surface thickness tomogram to illustrate the general condition of the
232 tested concrete deck. The majority of the indicated anomalies are predominantly top
233 delaminations (presented in red) based on the IES results. The gray color represents areas in
234 which the normalized thickness results were less than or equal to a value of 1.2, which are
235 indicative of “sound concrete”. Yellow represents areas with normalized thickness of 1.2 to 1.7,
236 or areas with incipient concrete delaminations. The quantity of areas with incipient
237 delaminations (plotted in yellow) detected from the BDS was estimated to be 135 sq ft (12.5 sq
238 meter) or 13.5% of the tested deck surface area. Areas with incipient delaminations and
239 delaminations deeper than 3-4 inches or 75 to 100 mm are not likely to be audibly detected by
240 human ears using chain drags for acoustic sounding (very subjective and dependent on chain
241 drag operators). Areas where the normalized thickness is greater than 1.7 are plotted in red,
242 which represents areas with probable top shallow concrete delaminations. These top
243 delaminated areas are likely detectable by human ears using acoustic sounding as a hollow,
244 drummy sound versus a high frequency sound from undamaged, good quality concrete. The
245 quantity of probable delaminations (plotted in red) detected from the BDS was estimated to be
246 149 sq ft (13.8 sq meter) or 14.6% of the tested deck surface area. The quantity of both
247 probable delaminations and incipient delaminations (plotted in yellow and red) detected from the
248 BDS was estimated to be 285 sq ft (26.5 sq meter) or 28.1% of the tested deck surface area.
249 Approximate data analysis of the IES data was 4 hours and 2 – 4 additional hours were required
250 for the results plotting process.

251

252 **Comparisons between the BDS-IES Test Results, Chain Dragging and Cores**

253

254 For comparison purposes, Rutgers University performed acoustic sounding using chain dragging
255 and hammer sounding to listen to the hollow sounds from shallow top delaminations of the
256 concrete deck. The delamination map from chain drags is presented in Figure 6. In addition,
257 eight cores were taken from the deck. The delamination map from the BDS-IES component
258 agreed well with the visual observations of the eight cores. Photographs of two (of eight) cores
259 are shown in Figure 7. Review of Figure 7 indicates that the test results from the BDS-IES
260 component correctly identified both shallow (Core # 5) and deeper delaminations (Core # 3),
261 where-as chain dragging only correctly identified shallow delaminations (Core # 5 - 2.5 inches or
262 63.5 mm deep) and failed to identify deeper delamination (Core # 3 – 3.5 inches or 88.9 mm
263 deep).

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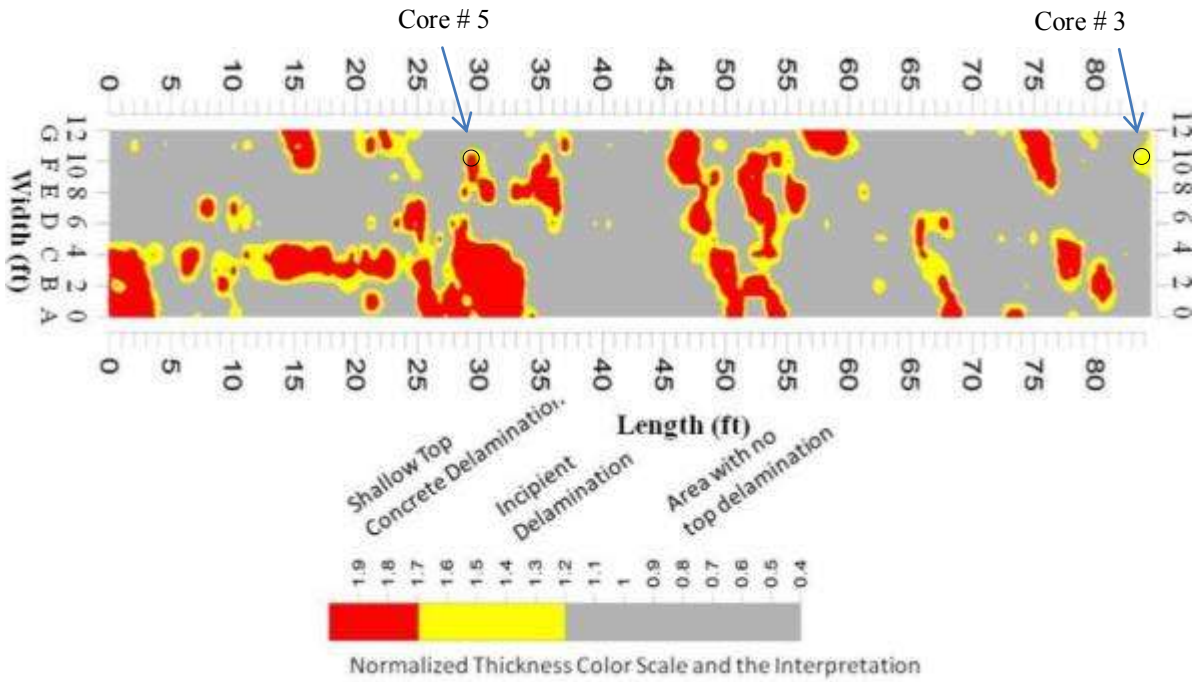


Figure 5 – Top Concrete Delamination Map from the BDS System – Impact Echo Scanning

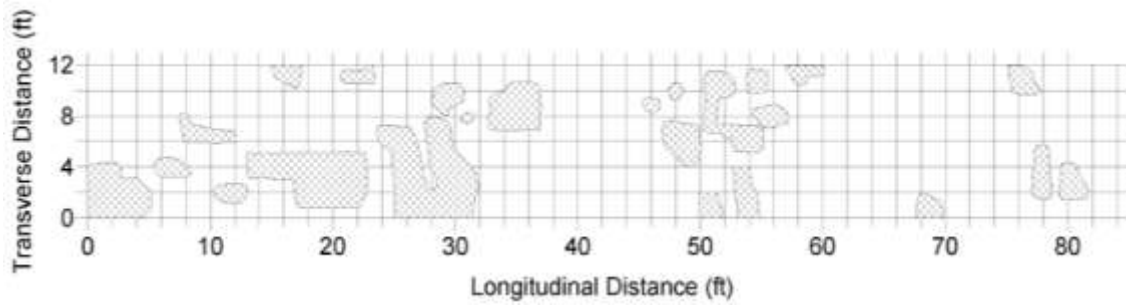


Figure 6 – Top Concrete Delamination Map from Chain Drags



Core # 5 - Delamination Depth at 2.5 inches



Core # 3 - Delamination Depth at 3.5 inches

Figure 7 – Photographs of Cores # 5 and #3 (Courtesy of Rutgers University)

311 **SECOND CASE STUDY: BRIDGE DECK SCANNER USING SPECTRAL ANALYSIS**
312 **OF SURFACE WAVES SCANNING ON AN ASPHALT OVERLAID CONCRETE DECK**
313

314 **Project Background**
315

316 An internal research project was conducted by the research team at Olson Engineering with
317 support from the Colorado Department of Transportation (CDOT) – Region 6 to evaluate the
318 internal condition of a concrete bridge deck with asphalt overlays, without removing the asphalt.
319 Structure E-17-IE: I-270 eastbound bridge over South Platte River (asphalt covered concrete
320 deck without water-proofing membrane) was selected for this study.
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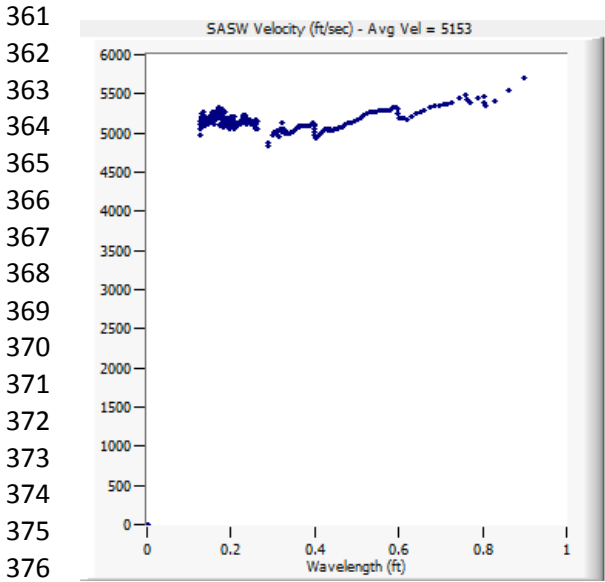
322 **Non-Destructive Evaluation Test Methods for Asphalt Overlaid Concrete Deck to Detect**
323 **Concrete Delamination**
324

325 A Bridge Deck Scanner (BDS) system using the Spectral Analysis of Surface Waves (SASW)
326 method was used to assess the bridge deck condition, with scanning conducted through the
327 asphalt. For this setup, the solenoid impactors were turned on for one transducer wheel and off
328 for the second transducer wheel. This setup allows the Impact Echo Scanning and Spectral
329 Analysis of Surface Wave Scanning to be performed simultaneously in a single scan. However,
330 in this case, only SASW data were used in the analysis. The background and theory of the
331 SASW test method can be found in many publications (4 and 5). The SASW scanning was
332 performed on the second span (between Pier 2 and Pier 3) of the bridge between a distance of 4 –
333 8 feet (1.22 – 2.44 meter) from the left rail on the left lane and shoulder. Each scan line started
334 approximately 11 feet (3.35 meter) from the west joint and ended approximately 2.6 feet (0.79
335 feet) from the east joint.
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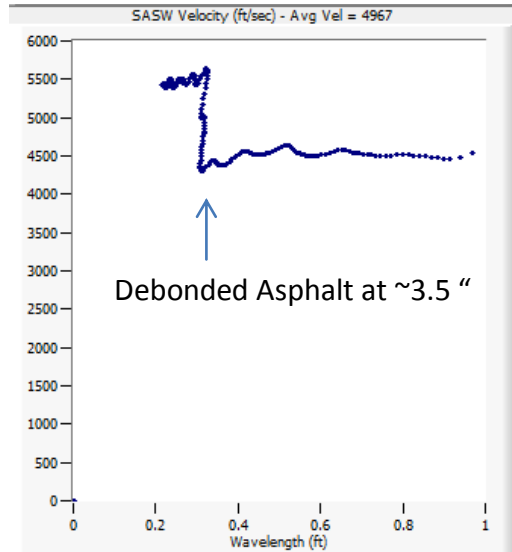
337 **SASW Data Interpretation**
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339 Figures 8a – 8d present example SASW test records and the corresponding data interpretations
340 from the asphalt overlaid deck. The plot shows the dispersion curve presenting the surface wave
341 velocity vs wavelength (or depth in the deck). Sound concrete (with no asphalt debonding)
342 yields a high and relatively constant surface wave velocity shown as a flat and horizontal line in
343 a dispersion curve throughout the depth of the bridge deck. A typical example of this case is
344 shown in Figure 8a. Olson Engineering has found that the presence of a sharp drop in the surface
345 wave velocity within the dispersion curve acts as a reliable indication of either potential
346 debonding between the asphalt (and between layers of asphalt pavements) and concrete and/or
347 delamination within the concrete layer. The location (wavelength) of the velocity drop relates to
348 the depth of either the debonding or delamination. This sudden drop of surface wave velocity is
349 then automatically detected by the BDS software to locate the depth of discontinuity (either
350 asphalt debonding or concrete delamination). The depth of the detected discontinuity is then
351 used to determine if discontinuity is in the asphalt layer, between the asphalt and concrete or
352 within the concrete layer. Figure 8b presents a dispersion curve (surface wave velocity vs
353 wavelength) from a location with possible asphalt debonding where a velocity drop is located at
354 a depth of 3.5 inches (88.9 mm) from the surface. Figure 8c presents a dispersion curve from a
355 location with apparently both asphalt debonding and bottom concrete delamination where two
velocity drops are detected at 3.2 inches (81.3 mm) and 7.4 inches (187.9 mm) from the surface.

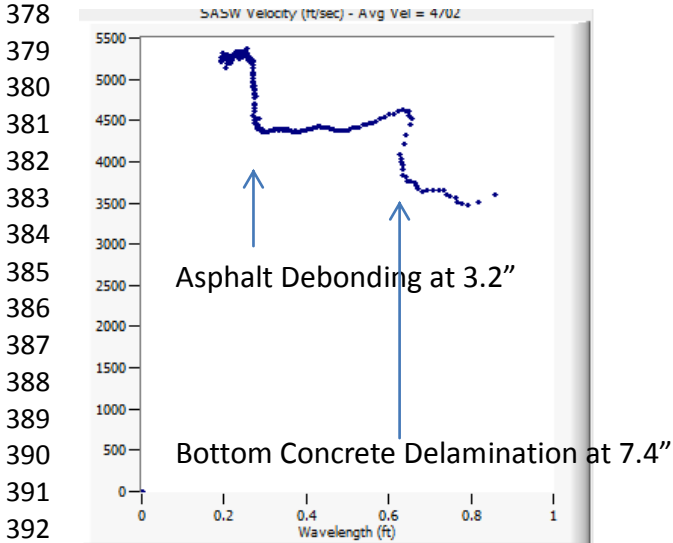
357 Note that the destructive verification of bottom delamination conditions were not performed due
 358 to safety concerns during coring. Figure 8d presents dispersion curves from locations with
 359 apparent top concrete delaminations where the depths (wavelengths) of the velocity drops are
 360 indicative of the top reinforcement depths.



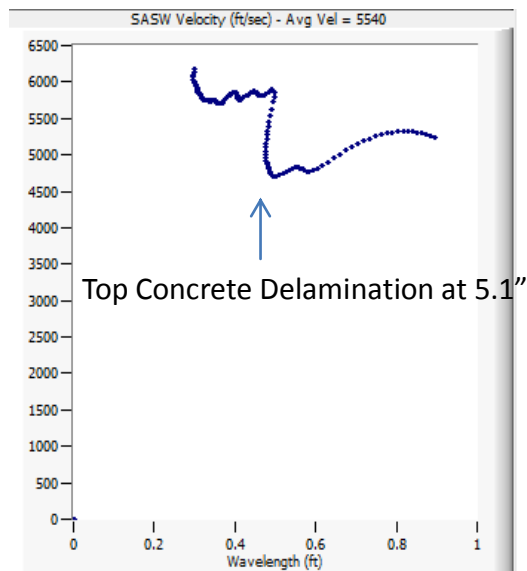
377 Figure 8a – Sound Concrete



377 Figure 8b- Debonded Asphalt on Sound Concrete



394 Figure 8c – Debonded Asphalt on Concrete
 395 With Bottom Delamination



394 Figure 8d – Top Concrete Delamination

397 **Figure 8 – SASW Data Interpretation for an Asphalt Overlaid Deck**

400 Top Delamination Map from the BDS - SASW Component

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402 A section of test results is presented in Figure 9a. In general for the condition ratings in Figures 9
403 - 14, each color represents different conditions as follows: “Pink” represents areas with apparent
404 asphalt debonding (0.2-0.33 feet or 61 – 100.6 mm), “Yellow” represents areas with either
405 asphalt debonding or top concrete delamination (0.33-0.41 feet or 100.6 – 125 mm), “Red”
406 represents areas with apparent top steel concrete delamination (0.41-0.55 feet or 125 – 167.6
407 mm) and “Grey” represents sound concrete with no potential top concrete delamination.

408

409 Comparisons between the SASW Test Results and Actual Conditions

410

411 After the completion of the initial BDS scanning, the asphalt overlay was removed to expose the
412 concrete and hydro-blasting was performed to remove loose/weak concrete. Due to time
413 limitations of night work, CDOT did not perform chain dragging on the bare deck of this
414 structure after the asphalt was removed. During the hydro-blasting process, approximately 2 –
415 2.5 inches (50 to 62 mm) of concrete was removed from the entire deck. However, deeper
416 concrete was removed in the areas with weaker, apparently delaminated concrete. Figure 9b
417 shows the concrete condition of this deck (same section where the SASW test results are
418 presented in Figure 9a) after hydro blasting. Note that dashed lines are added to Figure 9b to
419 outline one area in the foreground which is clearly worse than the rest of the deck. The area
420 within the dashed lines compare very well with the top delamination map shown in Figure 9a.
421 Note that additional areas around the 70 foot (21.3 meter) distance mark also appear to have
422 extensive exposed rebar indicative of delamination exposed by hydro-blasting. This also
423 matches well with the SASW scanning results plot (Figure 9a).

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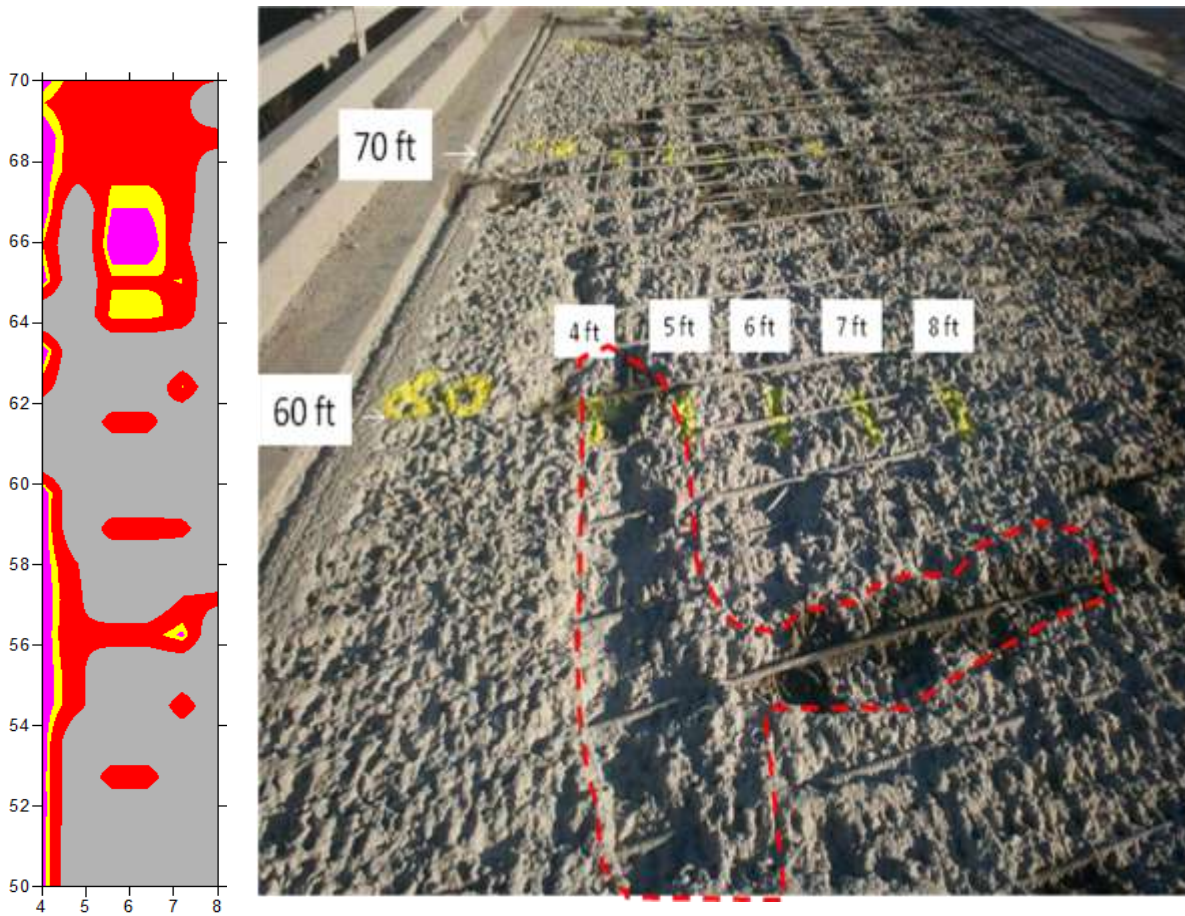


Figure 9a (left plot) – Top Concrete Delamination Map from the BDS – SASW component
Figure 9b (right photograph) – Actual Concrete Condition after Hydro Blasting Process

CONCLUSIONS

Funded and internal research have shown the ability of the Bridge Deck Scanner with Impact Echo and Spectral Analysis of Surface Waves technologies to accurately identify top and possibly bottom concrete delaminations and general concrete integrity for bare and asphalt overlaid concrete decks. An important finding was the ability of surface waves to penetrate debonded asphalt and detect underlying corrosion induced top and/or bottom delaminations associated with corrosion of the top and bottom deck reinforcement. Thus, deck repair/replacement decisions can be made with typically a 0.5 to 1 square foot (0.022 to 0.09 square meters) resolution of delamination/damage. The BDS-IE/SASW system is applicable to bare concrete or asphalt overlaid decks.

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